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Chapter 4: Vector-Valued Functions

Topic- Curves in Space, Limits and Continuity,
Derivatives and Motion, Differentiation Rules for Vector
Function, Vector Functions of Constant Length

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Vector calculus

Chapter - I

Vector - Valued Functions

Defⁿ - Vector valued function -

A vector valued function is defined as

$$\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j}$$

$$\text{or } \vec{r}(t) = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$$

where the components f, g, h are real valued function of the parameter t .

The vector valued fⁿ are also written in the following form

$$\vec{r}(t) = (f(t), g(t))$$

$$\text{or } \vec{r}(t) = (f(t), g(t), h(t))$$

Ex. Find the domain of $\vec{r}(t)$ & the value of $\vec{r}(t_0)$

1) $\vec{r}(t) = \cos t \vec{i} - 3t \vec{j}$, $t_0 = \pi$

Domain = $\{t \in \mathbb{R}\} = \mathbb{R}$

$$\begin{aligned} \vec{r}(\pi) &= \cos \pi \vec{i} - 3\pi \vec{j} \\ &= (-1)\vec{i} - 3\pi \vec{j} \\ &= -\vec{i} - 3\pi \vec{j} \end{aligned}$$

$$\begin{aligned} \cos n\pi &= (-1)^n \\ \sin n\pi &= 0 \end{aligned}$$

2) $\vec{r}(t) = \sqrt{3t+1} \vec{i} + t^2 \vec{j}$, $t_0 = 1$

$$\begin{aligned} \text{domain} &= \{t \in \mathbb{R} / 3t+1 \geq 0\} \\ &= \{t \in \mathbb{R} / t \geq -\frac{1}{3}\} \end{aligned}$$

$$\begin{aligned} \vec{r}(1) &= \sqrt{3(1)+1} \vec{i} + 1 \vec{j} \\ &= 2\vec{i} + \vec{j} \quad \text{or } \pm 2\vec{i} + \vec{j} \end{aligned}$$

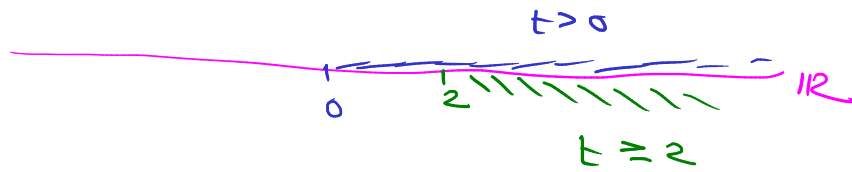
$$\sqrt{4} = \pm 2$$

$$3) \vec{r}(t) = \cos \pi t \vec{i} - \ln t \vec{j} + \sqrt{t-2} \vec{k}, \quad t_0 = 3$$

$$\Rightarrow \cos \pi t \Rightarrow t \in \mathbb{R}$$

$$\ln t \Rightarrow t > 0$$

$$\sqrt{t-2} \Rightarrow t-2 \geq 0 \Rightarrow t \geq 2$$



$$\text{domain} = \{t \in \mathbb{R} \mid t \geq 2\}$$

$$\begin{aligned} \vec{r}(3) &= \cos 3\pi \vec{i} - \ln 3 \vec{j} + \sqrt{3-2} \vec{k} \\ &= (-1)^3 \vec{i} - \ln 3 \vec{j} + 1 \vec{k} \\ &= -\vec{i} - \ln 3 \vec{j} + \vec{k} \end{aligned}$$

$$\text{Ex. } \vec{r}(t) = 2e^{-t} \vec{i} + \sin^{-1} t \vec{j} + \ln(1-t) \vec{k}, \quad t_0 = 0$$

$$e^{-t} \Rightarrow t \in \mathbb{R}$$

$$\sin^{-1}(t) \Rightarrow -1 \leq t \leq 1$$

$$\ln(1-t) \Rightarrow 1-t > 0$$

i.e.

$$1 > t$$

$$\text{or } t < 1$$

$$\theta = \sin^{-1}(2)$$

$$\Rightarrow \sin \theta = 2$$

$$-1 \leq \sin \theta \leq 1$$

For $\sin^{-1}(t)$

$$-1 \leq t \leq 1$$



$$-1 \leq t < 1$$

$$\text{domain of } \vec{r}(t) = \{t \in \mathbb{R} \mid -1 \leq t < 1\}$$

$$\text{Ex. } \vec{r}(t) = 3t \tan t \vec{i} + 4 \sec t \vec{j} + 5t \vec{k}, \quad \vec{r}(0), \vec{r}\left(\frac{\pi}{2}\right), \vec{r}\left(\frac{3\pi}{2}\right)$$

$$\Rightarrow \tan t = \frac{\sin t}{\cos t}, \quad \tan t \text{ is not defined if } \cos t = 0 \Rightarrow t = \frac{\pi}{2}, \frac{3\pi}{2}, \frac{4\pi}{2}$$

$$\cos t = 0 \Rightarrow t = (2n+1) \frac{\pi}{2}, \quad n=0, \pm 1, \pm 2, \dots$$

$$\& \sin t = 0 \Rightarrow t = n\pi$$

$\tan t$ exist if $t \neq (2n+1) \frac{\pi}{2}$

$\sec t = \frac{1}{\cos t}$ exist if $t \neq (2n+1) \frac{\pi}{2}$

\therefore domain $\vec{r}(t) = \left\{ t \in \mathbb{R} \mid t \neq (2n+1) \frac{\pi}{2} \right\}$

$$\begin{aligned} \vec{r}(0) &= 3 \tan(0) \vec{i} + 4 \sec(0) \vec{j} + 5(0) \vec{k} \\ &= 0 \vec{i} + 4(1) \vec{j} + 0 \vec{k} = 4 \vec{j} \end{aligned}$$

$$\begin{aligned} \vec{r}\left(\frac{\pi}{2}\right) &= 3 \tan\left(\frac{\pi}{2}\right) \vec{i} + 4 \sec\left(\frac{\pi}{2}\right) \vec{j} + 5 \frac{\pi}{2} \vec{k} \\ &= \text{does not exist.} \end{aligned}$$

$$\tan \frac{\pi}{2} = \frac{\sin \frac{\pi}{2}}{\cos \frac{\pi}{2}} = \frac{1}{0}$$

$$\begin{aligned} \vec{r}\left(\frac{2\pi}{3}\right) &= 3 \tan\left(\frac{2\pi}{3}\right) \vec{i} + 4 \sec\left(\frac{2\pi}{3}\right) \vec{j} + 5\left(\frac{2\pi}{3}\right) \vec{k} \\ &= 3(-\sqrt{3}) \vec{i} + 4(-2) \vec{j} + \frac{10\pi}{3} \vec{k} \\ &= -3\sqrt{3} \vec{i} - 8 \vec{j} + \frac{10\pi}{3} \vec{k}. \end{aligned}$$

= not define.

* Limit of vector valued Function -

Let $\vec{r}(t) = f(t) \vec{i} + g(t) \vec{j} + h(t) \vec{k}$ be a vector function with domain D & let $\vec{L} = L_1 \vec{i} + L_2 \vec{j} + L_3 \vec{k}$ be a vector. Then we say that \vec{L} is the limit of the vector-valued function $\vec{r}(t)$ as $t \rightarrow t_0$ if for every $\epsilon > 0$, $\exists \delta > 0$ s.t. $\forall t \in D$

$$|\vec{r}(t) - \vec{L}| < \epsilon \quad \text{whenever } 0 < |t - t_0| < \delta$$

we can denote this as

$$\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{L}$$

Remark - If $\vec{r}(t) = f(t) \vec{i} + g(t) \vec{j} + h(t) \vec{k}$ and

$$\vec{L} = L_1 \vec{i} + L_2 \vec{j} + L_3 \vec{k} \quad \text{then} \quad \lim_{t \rightarrow t_0} \vec{r}(t) = \vec{L}$$

if & only if $\lim_{t \rightarrow t_0} f(t) = L_1$, $\lim_{t \rightarrow t_0} g(t) = L_2$

§ $\lim_{t \rightarrow t_0} h(t) = J_3$, Hence we have

$$\lim_{t \rightarrow t_0} \vec{r}(t) = \left[\lim_{t \rightarrow t_0} f(t) \right] \vec{i} + \left[\lim_{t \rightarrow t_0} g(t) \right] \vec{j} + \left[\lim_{t \rightarrow t_0} h(t) \right] \vec{k}$$

* **Continuity of vector valued function-**

Let $\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$ be a vector function with domain D . Then the vector-valued function $\vec{r}(t)$ is said to be continuous at $t = t_0$ if

$$\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{r}(t_0)$$

The function is continuous if it is continuous at every point in its domain.

* **Derivative of vector-valued function -**

Let $\vec{r}(t)$ be a vector-valued function with domain D . Then the vector-valued function $\vec{r}(t)$ is said to be differentiable at $t = t_0$ if

$$\lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t_0 + \Delta t) - \vec{r}(t_0)}{\Delta t} \text{ is exist and finite.}$$

It is denoted by

$$\frac{d}{dt} \vec{r}(t_0) \text{ or } \vec{r}'(t_0) \text{ or } \left(\frac{d\vec{r}}{dt} \right)_{t=t_0}$$

$$\frac{d}{dt} \vec{r}(t) = \vec{r}'(t) = \lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t}$$

* **Remark -**

1] A vector function $\vec{r}(t)$ is differentiable if it is differentiable at every point of its domain.

2] A vector function $\vec{r}(t)$ is diff. function of t iff the components $f(t), g(t), h(t)$ are diff. functions of t .

3] The curve trace by $\vec{r}(t)$ is smooth if $\frac{d\vec{r}}{dt}$ is continuous & $\frac{d\vec{r}}{dt} \neq 0$ for any t that is if f, g, h have conti first derivatives that are not simultaneously zero.

4) A curve that is made up of a finite number of smooth curves pieced together in a continuous fashion is called piecewise smooth.



5) If \vec{r} is position vector of a particle moving along a smooth curve in space then

i) $\vec{v}(t) = \frac{d}{dt} \vec{r}(t)$ is the particle velocity vector, tangent to the curve at any time t , the direction of \vec{v} is the direction of motion.

ii) speed is the magnitude of velocity $\vec{v}(t)$
 i.e. speed = $|\vec{v}(t)|$
 If $\vec{r} = a\vec{i} + b\vec{j} + c\vec{k}$
 $|\vec{r}| = \sqrt{a^2 + b^2 + c^2}$

iii) Acceleration is the derivative of velocity i.e.
 $\vec{a}(t) = \frac{d}{dt} \vec{v}(t) = \frac{d^2}{dt^2} \vec{r}(t)$

iv) The unit vector $\hat{v} = \frac{\vec{v}}{|\vec{v}|}$ is the direction of motion at time t .

v) The tangent line to a smooth curve $\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$ at $t = t_0$ is the line that passes through the point $(f(t_0), g(t_0), h(t_0))$ parallel to $\vec{v}(t_0)$, the curve's velocity vector at t_0 .

[Eqⁿ of line passing through (x_0, y_0, z_0) and dir.s. a, b, c is

$$\frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c} = \lambda$$

$$\frac{x-x_0}{a} = \lambda \Rightarrow x = a\lambda + x_0$$

$$y = y_0 + b\lambda \quad \& \quad z = z_0 + c\lambda$$

Ex. Evaluate e

$$\begin{aligned} \lim_{t \rightarrow 0} [e^{-t} \cos t \mathbf{i} + e^{-t} \sin t \mathbf{j} + e^{-t} \mathbf{k}] \\ = e^0 \cos 0 \mathbf{i} + e^0 \sin 0 \mathbf{j} + e^0 \mathbf{k} \\ = \mathbf{i} + 0 \mathbf{j} + \mathbf{k} = \mathbf{i} + \mathbf{k} \end{aligned}$$

Ex. Evaluate e

$$\begin{aligned} \lim_{t \rightarrow \infty} [2e^{-t} \mathbf{i} + e^{-t} \mathbf{j} + e^{-2t} \mathbf{k}] \\ = 2e^{-\infty} \mathbf{i} + e^{-\infty} \mathbf{j} + e^{-\infty} \mathbf{k} = \mathbf{0} \end{aligned}$$

$$e^{-\infty} = 0$$

$$e^{\infty} = \infty$$

Ex.

$$\lim_{t \rightarrow 0} \left[\frac{\sin t}{t} \mathbf{i} + \frac{\tan^2 2t}{\sin 2t} \mathbf{j} + \frac{t^3 - 8}{t + 2} \mathbf{k} \right]$$

$$= \lim_{t \rightarrow 0} \frac{\sin t}{t} \mathbf{i} + \lim_{t \rightarrow 0} \frac{\tan^2 2t}{\sin 2t} \mathbf{j}$$

$$+ \lim_{t \rightarrow 0} \frac{t^3 - 8}{t + 2} \mathbf{k}$$

$$\lim_{\theta \rightarrow 0} \frac{\sin \theta}{\theta} = 1$$

$$\lim_{t \rightarrow 0} \frac{\tan^2 \theta}{\sin \theta} = 0$$

L'Hospital rule

$$\lim_{t \rightarrow 0} \frac{2 \tan 2t \cdot \sec^2 2t \cdot 2}{\cos 2t \cdot 2}$$

$$= \mathbf{i} + \lim_{t \rightarrow 0} \frac{2 \tan 2t \cdot \sec^2 2t \cdot 2}{\cos 2t \cdot 2} \mathbf{j} + \frac{-8}{2} \mathbf{k}$$

$$\tan 0 = 0$$

$$= \mathbf{i} + \frac{2 \tan 0 \cdot \sec^2 0}{\cos 0} \mathbf{j} - 4 \mathbf{k}$$

$$= \mathbf{i} + 0 \mathbf{j} - 4 \mathbf{k} = \mathbf{i} - 4 \mathbf{k}$$

Ex.

$$\lim_{t \rightarrow \frac{\pi}{6}} [\cos^2 t \mathbf{i} + \sin^2 t \mathbf{j} + \mathbf{k}]$$

$$\cos \frac{\pi}{6} = \cos 30$$

$$= \cos^2 \frac{\pi}{6} \mathbf{i} + \sin^2 \frac{\pi}{6} \mathbf{j} + \mathbf{k}$$

$$= \frac{\sqrt{3}}{2}$$

$$= \left(\frac{\sqrt{3}}{2}\right)^2 \mathbf{i} + \left(\frac{1}{2}\right)^2 \mathbf{j} + \mathbf{k}$$

$$\sin 30 = \frac{1}{2}$$

$$= \frac{3}{4} \mathbf{i} + \frac{1}{4} \mathbf{j} + \mathbf{k}$$

Ex.

$$\lim_{t \rightarrow \infty} \left[2e^{-2t} \mathbf{i} + \frac{2t+3}{3t-1} \mathbf{j} + \tan^{-1} 2t \mathbf{k} \right]$$

$$= \lim_{t \rightarrow \infty} 2e^{-2t} \mathbf{i} + \lim_{t \rightarrow \infty} \frac{2t+3}{3t-1} \mathbf{j} + \lim_{t \rightarrow \infty} \tan^{-1} 2t \mathbf{k}$$

L'Hospital rule

$$= 2e^{-\infty} \mathbf{i} + \lim_{t \rightarrow \infty} \frac{2}{3} \mathbf{j} + \tan^{-1} \infty \mathbf{k}$$

$$= 2(0) \mathbf{i} + \frac{2}{3} \mathbf{j} + \frac{\pi}{2} \mathbf{k}$$

$$= \frac{2}{3} \mathbf{j} + \frac{\pi}{2} \mathbf{k}$$

$$\begin{aligned} \sin(t-2)^2 \\ = \sin^2(t-2) \end{aligned}$$

Ex.

$$\lim_{t \rightarrow 2} \left[\frac{\sin^2(t-2)}{t-2} \mathbf{i} + \frac{t^2-4}{t-2} \mathbf{j} \right]$$

L'Hospital rule

$$= \lim_{t \rightarrow 2} \frac{2 \sin(t-2) \cdot \cos(t-2)}{1} \mathbf{i} + \lim_{t \rightarrow 2} \frac{2t}{1} \mathbf{j}$$

$$= 2 \sin 0 \cos 0 \mathbf{i} + 4 \mathbf{j} = 4 \mathbf{j}$$

Ex. Discuss the conti of the following fⁿ

$$\vec{f}(t) = \begin{cases} \sin \frac{t}{2} \mathbf{i} + \cos \frac{2t}{3} \mathbf{j} + \tan \frac{5t}{4} \mathbf{k}, & t \neq \pi \\ \mathbf{i} - \frac{1}{2} \mathbf{j} + \mathbf{k}, & t = \pi \end{cases}$$

⇒ consider

$$\lim_{t \rightarrow \pi} \vec{f}(t) = \lim_{t \rightarrow \pi} \left[\sin \frac{t}{2} \mathbf{i} + \cos \frac{2t}{3} \mathbf{j} + \tan \frac{5t}{4} \mathbf{k} \right]$$

$$= \sin \frac{\pi}{2} \mathbf{i} + \cos \frac{2\pi}{3} \mathbf{j} + \tan \frac{5\pi}{4} \mathbf{k}$$

$$= \mathbf{i} - \frac{1}{2} \mathbf{j} + \mathbf{k}$$

$$= \mathbf{i} - \frac{1}{2} \mathbf{j} + \mathbf{k}$$

at $t = \pi$

$$\vec{f}(t) = \vec{f}(\pi) = \mathbf{i} - \frac{1}{2} \mathbf{j} + \mathbf{k}$$

$$\therefore \lim_{t \rightarrow \pi} \vec{f}(t) = \vec{f}(\pi)$$

∴ $\vec{f}(t)$ is conti at $t = \pi$.

$$\begin{aligned} \cos \frac{2\pi}{3} &= \cos \left(\pi - \frac{\pi}{3} \right) \\ &= -\cos \frac{\pi}{3} \\ &= -\frac{1}{2} \end{aligned}$$

$$\begin{aligned} \tan \frac{5\pi}{4} &= \tan \left(\pi + \frac{\pi}{4} \right) \\ &= \tan \frac{\pi}{4} \\ &= 1 \end{aligned}$$

Ex.

$$f(t) = \begin{cases} t^3 i + \sin \frac{\pi}{2} t j + \ln(t+2) k, & t \neq -1 \\ -i - j, & t = -1 \end{cases}$$

$$\begin{aligned} \Rightarrow \lim_{t \rightarrow -1} f(t) &= \lim_{t \rightarrow -1} \left[t^3 i + \sin \frac{\pi}{2} t j + \ln(t+2) k \right] \\ &= -i + \sin\left(-\frac{\pi}{2}\right) j + \ln(-1+2) k \\ &= -i - j + 0 \\ &= -i - j \end{aligned}$$

$\sin(-\theta)$
 $= -\sin\theta$

$\therefore \lim_{t \rightarrow -1} f(t) \neq f(-1)$

$\therefore f(t)$ is discontinuous at $t = -1$

Ex.

$$f(t) = \begin{cases} \frac{t^2-1}{\ln t} i + \frac{\sqrt{t}-1}{1-t} j + \tan^{-1}(t) k, & t \neq 1 \\ 2i - \frac{1}{2}j + \frac{\pi}{4}k, & t = 1 \end{cases}$$

$$\begin{aligned} \Rightarrow \lim_{t \rightarrow 1} f(t) &= \lim_{t \rightarrow 1} \left[\frac{t^2-1}{\ln t} \right] i + \lim_{t \rightarrow 1} \frac{\sqrt{t}-1}{1-t} j \\ &\quad + \lim_{t \rightarrow 1} \tan^{-1}(t) k \end{aligned}$$

by L'Hospital rule

$$\begin{aligned} &= \lim_{t \rightarrow 1} \frac{2t}{\frac{1}{t}} i + \lim_{t \rightarrow 1} \frac{\frac{1}{2\sqrt{t}}}{-1} j \\ &\quad + \lim_{t \rightarrow 1} \tan^{-1}(1) k \end{aligned}$$

$$= 2i - \frac{1}{2}j + \frac{\pi}{4}k$$

since $f(1) = 2i - \frac{1}{2}j + \frac{\pi}{4}k$

$\therefore \lim_{t \rightarrow 1} f(t) = f(1)$

$\therefore f(t)$ is continuous at $t = 1$

Ex.
$$\vec{f}(t) = \begin{cases} \frac{\sin t}{t} \vec{i} + \frac{\tan^2 t}{\sin 2t} \vec{j} + \frac{t^3 - 8}{t+2} \vec{k}, & t \neq 0 \\ \vec{i} + \vec{j} - 4\vec{k} & , t = 0 \end{cases}$$

$$\Rightarrow \lim_{t \rightarrow 0} \vec{f}(t) = \lim_{t \rightarrow 0} \frac{\sin t}{t} \vec{i} + \lim_{t \rightarrow 0} \frac{\tan^2 t}{\sin 2t} \vec{j} + \lim_{t \rightarrow 0} \frac{t^3 - 8}{t+2} \vec{k}$$

$$= \vec{i} + \lim_{t \rightarrow 0} \frac{2 \tan t \cdot \sec^2 t}{\cos 2t \cdot 2} \vec{j} + \frac{(-8)}{2} \vec{k}$$

$$= \vec{i} + 0 \vec{j} - 4\vec{k}$$

$$= \vec{i} - 4\vec{k}$$

Now $\vec{f}(0) = \vec{i} + \vec{j} - 4\vec{k}$

$\therefore \lim_{t \rightarrow 0} \vec{f}(t) \neq \vec{f}(0)$

$\therefore \vec{f}(t)$ is not conti at $t=0$.

* Chain Rule -

Let $\vec{u}(s) = a(s)\vec{i} + b(s)\vec{j} + c(s)\vec{k}$ be a vector function of s and $s = f(t)$ is a differential scalar function of t then

$$\frac{d}{dt} \vec{u}(s) = \frac{d}{ds} \vec{u}(s) \cdot \frac{ds}{dt}$$

$$= \frac{d}{ds} \vec{u}(f(t)) \cdot \frac{d}{dt} f(t)$$

* Thm - Vector functions of constant length -

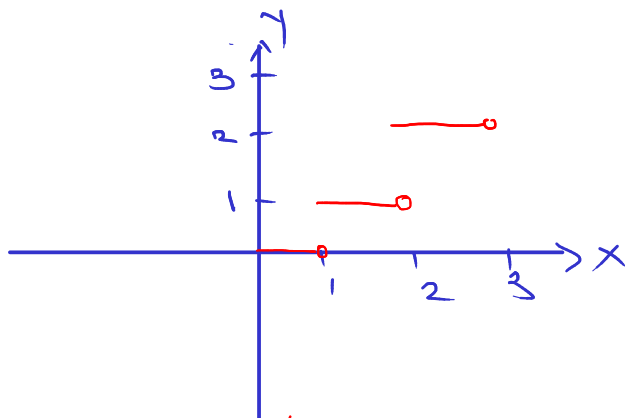
If $\vec{r}(t)$ is a differentiable vector function of t and length of $\vec{r}(t)$ is constant then

$$\vec{r} \cdot \frac{d\vec{r}}{dt} = 0$$

Ex. Discuss the continuity of the function

$$\vec{f}(t) = \cos t \vec{i} + \sin t \vec{j} + [t] \vec{k}$$

where $[t]$ is the greatest integer function.



$$\begin{aligned}
 f(x) &= 0, & 0 \leq x < 1 \\
 f(2 \cdot 1) &= 2, & 2 < 2 \cdot 1 < 3 \\
 f(4 \cdot 5) &= 4, & 4 < 4 \cdot 5 < 5 \\
 f(x) &= 5, & 5 \leq x < 6 \\
 & & x & \quad y = f(x) \\
 & & 0 \leq x < 1 & \quad 0 \\
 & & 1 \leq x < 2 & \quad 1
 \end{aligned}$$

$\sin x / \cos x$

$\sin x$ & $\cos x$ are conti for $\forall t \in \mathbb{R}$. but $[t]$ is disconti at every integers. Therefore $\bar{f}(t)$ is disconti at every integers.

Ex. If $\vec{r}(t) = \frac{t}{t+1} \vec{i} + \frac{1}{t} \vec{j}$ is the position value of particle in the xy plane at time t . Find an equation in x & y whose graph is the path of the particle. Then find the particles velocity & acceleration vectors at $t = -\frac{1}{2}$.

\Rightarrow

since

$$\vec{r} = x\vec{i} + y\vec{j}$$

$$\therefore x = \frac{t}{t+1} \quad \& \quad y = \frac{1}{t}$$

$$\frac{1}{x} = \frac{t+1}{t} = 1 + \frac{1}{t} = 1 + y$$

$$\therefore \frac{1}{x} - 1 = y$$

$$\text{or } y = \frac{1}{x} - 1$$

This is required eqⁿ whose graph is path of the particle.

$$\vec{r}(t) = \frac{t}{t+1} \vec{i} + \frac{1}{t} \vec{j}$$

$$\text{velocity} = \vec{v}(t) = \frac{d}{dt} \vec{r} = \frac{(t+1)(1) - t(1)}{(t+1)^2} \vec{i} - \frac{1}{t^2} \vec{j}$$

$$\vec{v}(t) = \frac{1}{(t+1)^2} \vec{i} - \frac{1}{t^2} \vec{j}$$

$$\text{at } t = -\frac{1}{2} \quad \vec{v}\left(-\frac{1}{2}\right) = \frac{1}{\frac{1}{4}} \vec{i} - \frac{1}{\frac{1}{4}} \vec{j} = 4\vec{i} - 4\vec{j}$$

$$\begin{aligned}
 \vec{r} &= x\vec{i} + y\vec{j} \\
 \vec{r} &= x\vec{i} + y\vec{j} + z\vec{k}
 \end{aligned}$$

$$\frac{d}{dt} = \frac{v \cdot v' - v v'}{v^2}$$

$$\text{acc.} = \vec{a}(t) = \frac{d}{dt} \vec{v}(t) = \frac{-2}{(t+1)^3} \vec{i} + \frac{2}{t^3} \vec{j}$$

$$\text{at } t = -\frac{1}{2}$$

$$\begin{aligned} \vec{a}\left(-\frac{1}{2}\right) &= \frac{-2}{\left(\frac{1}{2}\right)^3} \vec{i} + \frac{2}{\left(\frac{1}{2}\right)^3} \vec{j} \\ &= -16\vec{i} - 16\vec{j} \end{aligned}$$

Ex. If $\vec{r}(t) = \sec t \vec{i} + (\tan t) \vec{j} + \frac{4}{3}t \vec{k}$ is the position of the particle in the space at time t . Find the particle velocity and acceleration vectors at $t = \frac{\pi}{6}$. Write the particles velocity at that time as the product of its speed & direction.

$$\Rightarrow \vec{r}(t) = \sec t \vec{i} + \tan t \vec{j} + \frac{4}{3}t \vec{k}$$

$$\text{Velocity} = \vec{v}(t) = \frac{d\vec{r}}{dt} = \sec t \cdot \tan t \vec{i} + \sec^2 t \vec{j} + \frac{4}{3} \vec{k}$$

$$\text{acc}^n = \vec{a}(t) = \frac{d\vec{v}}{dt} = [\sec t \cdot \sec^2 t + \sec t \tan t \cdot \tan t] \vec{i} + 2 \sec t \cdot \sec t \cdot \tan t \vec{j} + 0 \vec{k}$$

$$\text{at } t = \frac{\pi}{6}$$

$$\vec{v}\left(\frac{\pi}{6}\right) = \sec \frac{\pi}{6} \tan \frac{\pi}{6} \vec{i} + \sec^2 \frac{\pi}{6} \vec{j} + \frac{4}{3} \vec{k}$$

$$= \frac{2}{\sqrt{3}} \cdot \frac{1}{\sqrt{3}} \vec{i} + \frac{4}{3} \vec{j} + \frac{4}{3} \vec{k}$$

$$= \frac{2}{3} \vec{i} + \frac{4}{3} \vec{j} + \frac{4}{3} \vec{k}$$

$$\sec \frac{\pi}{6} = \frac{1}{\cos \pi/6}$$

$$\tan 30 = \frac{\sin 30}{\cos 30} = \frac{1/2}{\sqrt{3}/2} = \frac{1}{\sqrt{3}}$$

$$\begin{aligned} &= \frac{1}{\cos 30} \\ &= \frac{1}{\frac{\sqrt{3}}{2}} \\ &= \frac{2}{\sqrt{3}} \end{aligned}$$

$$\text{at } t = \frac{\pi}{6}$$

$$\vec{a}\left(\frac{\pi}{6}\right) = \left[\frac{8}{3\sqrt{3}} + \frac{2}{3\sqrt{3}} \right] \vec{i} + \frac{2}{3\sqrt{3}} \vec{j} + 0 \vec{k}$$

$$= \frac{10}{3\sqrt{3}} \vec{i} + \frac{2}{3\sqrt{3}} \vec{j}$$

$$\vec{r} = a\vec{i} + b\vec{j} + c\vec{k}$$

$$|\vec{r}| = \sqrt{a^2 + b^2 + c^2}$$

$$\text{speed} = |\vec{v}\left(\frac{\pi}{6}\right)| = \sqrt{\left(\frac{2}{3}\right)^2 + \left(\frac{4}{3}\right)^2 + \left(\frac{4}{3}\right)^2}$$

$$= \sqrt{\frac{4}{9} + \frac{16}{9} + \frac{16}{9}} = \frac{6}{3}$$

$$\text{direction} = \hat{u}\left(\frac{\pi}{6}\right) = \frac{\vec{u}}{|\vec{u}|} = \frac{1}{\frac{6}{\sqrt{3}}} \left[\frac{2}{3} \vec{i} + \frac{4}{3} \vec{j} + \frac{4}{3} \vec{k} \right]$$

$$= \frac{1}{2} \vec{i} + \frac{2}{3} \vec{j} + \frac{2}{3} \vec{k}$$

$$\text{velocity} = (\text{speed})(\text{direction})$$

$$= \frac{6}{3} \left[\frac{1}{3} \vec{i} + \frac{2}{3} \vec{j} + \frac{2}{3} \vec{k} \right]$$

Ex. If $\vec{r}(t) = e^{-t} \vec{i} + (2 \cos 3t) \vec{j} + 2 \sin 3t \vec{k}$ is the position of the particle in the space at time t . Find the particle velocity & acc. vectors at $t=0$. Write the particle velocity at that time as the product of its speed and direction.

$$\Rightarrow \vec{r}(t) = e^{-t} \vec{i} + (2 \cos 3t) \vec{j} + 2 \sin 3t \vec{k}$$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = -e^{-t} \vec{i} - 6 \sin 3t \vec{j} + 6 \cos 3t \vec{k}$$

$$\vec{a}(t) = \frac{d\vec{v}}{dt} = e^{-t} \vec{i} - 18 \cos 3t \vec{j} - 18 \sin 3t \vec{k}$$

at $t=0$

$$\vec{v}(0) = -\vec{i} - 0 \vec{j} + 6 \vec{k} = -\vec{i} + 6 \vec{k}$$

$$\text{speed} = |\vec{v}(0)| = \sqrt{(-1)^2 + 0^2 + 6^2} = \sqrt{1+36} = \sqrt{37}$$

$$\text{direction} = \frac{\vec{v}(0)}{|\vec{v}(0)|} = \frac{1}{\sqrt{37}} (-\vec{i} + 6 \vec{k})$$

$$\text{velocity} = \text{speed} \times \text{direction}$$

$$= \sqrt{37} \left[\frac{-\vec{i} + 6 \vec{k}}{\sqrt{37}} \right]$$

Ex. If $\vec{r}(t) = \frac{4}{9} (1+t)^{3/2} \vec{i} + \frac{4}{9} (1-t)^{3/2} \vec{j} + \frac{1}{3} t \vec{k}$ is the position of a particle in the space at time t . Find the angle between the velocity and acc. vectors at time $t=0$.

$$\Rightarrow \vec{r}(t) = \frac{4}{9} (1+t)^{3/2} \vec{i} + \frac{4}{9} (1-t)^{3/2} \vec{j} + \frac{1}{3} t \vec{k}$$

$$\vec{v}(t) = \frac{4}{9} \cdot \frac{3}{2} (1+t)^{1/2} \vec{i} + \frac{4}{9} \cdot \frac{3}{2} (1-t)^{1/2} (-1) \vec{j} + \frac{1}{3} \vec{k}$$

$$\vec{a}(t) = \frac{2}{3} \cdot \frac{1}{2} (1+t)^{-1/2} \vec{i} + \frac{2}{3} \cdot \frac{1}{2} (1-t)^{-1/2} \vec{j} + 0 \vec{k}$$

at $t=0$

$$\vec{v}(0) = \frac{2}{3}\vec{i} - \frac{2}{3}\vec{j} + \frac{1}{3}\vec{k}$$

$$\vec{a}(0) = \frac{1}{3}\vec{i} + \frac{1}{3}\vec{j} + 0\vec{k}$$

\therefore Angle betⁿ velocity & acc. at $t=0$ is

$$\cos\theta = \frac{\frac{2}{3}(\frac{1}{3}) + (-\frac{2}{3})(\frac{1}{3}) + (\frac{1}{3})(0)}{\sqrt{\frac{4}{9} + \frac{4}{9} + \frac{1}{9}} \sqrt{\frac{1}{9} + \frac{1}{9} + 0}}$$

$$= \frac{\frac{2}{9} - \frac{2}{9} + 0}{\sqrt{2/9}} = 0$$

$$\cos\theta = 0 \Rightarrow \theta = \frac{\pi}{2}$$

\therefore velocity & acc. at $t=0$ are perpendicular to each other.

Ex. Find parametric eq^s for the line that is tangent to the curve

$$\vec{r}(t) = \sin(t)\vec{i} + (t^2 - \cos t)\vec{j} + e^t\vec{k} \text{ at } t=0.$$

$$\Rightarrow \vec{r}(0) = \sin(0)\vec{i} + (0 - \cos 0)\vec{j} + e^0\vec{k}$$

$$\vec{r}(0) = 0\vec{i} - \vec{j} + \vec{k}$$

\therefore point on tgt line is $(0, -1, 1)$

For d.r.s. consider

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \cos t\vec{i} + (2t + \sin t)\vec{j} + e^t\vec{k}$$

$$\vec{v}(0) = \vec{i} + 0\vec{j} + \vec{k}$$

\therefore d.r.s. of tgt are $1, 0, 1$

\therefore Eqⁿ of tgt line passing through $(0, -1, 1)$ and having d.r.s. $1, 0, 1$ is

$$\frac{x-0}{1} = \frac{y+1}{0} = \frac{z-1}{1} = \lambda$$

$$\therefore x = \lambda, y = -1, z = \lambda + 1$$

If $\vec{u} = a_1\vec{i} + a_2\vec{j} + a_3\vec{k}$

$\vec{v} = b_1\vec{i} + b_2\vec{j} + b_3\vec{k}$

then angle betⁿ \vec{u} & \vec{v} is

$$\cos\theta = \frac{a_1b_1 + a_2b_2 + a_3b_3}{\sqrt{a_1^2 + b_1^2 + c_1^2} \sqrt{a_2^2 + b_2^2 + c_2^2}}$$

Ex. Find the values of t so that the tangent line to the curve $\vec{r}(t) = 2t\vec{i} + t^2\vec{j} - t^2\vec{k}$ contains the point $(0, -4, 4)$.

$$\Rightarrow \vec{r}(t) = 2t\vec{i} + t^2\vec{j} - t^2\vec{k}$$

point on the tangent line is $(2t, t^2, -t^2)$

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = 2\vec{i} + 2t\vec{j} - 2t\vec{k}$$

\therefore d.r.s. of tangent line $2, 2t, -2t$

eqn of tangent line is

$$\frac{x-2t}{2} = \frac{y-t^2}{2t} = \frac{z+t^2}{-2t} = \lambda$$

$$x = 2\lambda + 2t, \quad y = 2t\lambda + t^2, \quad z = -2t\lambda - t^2$$

Now $(0, -4, 4)$ lies on tangent line

$$\therefore 2\lambda + 2t = 0 \quad \text{--- (1)}$$

$$2t\lambda + t^2 = -4 \quad \text{--- (2)}$$

$$-2t\lambda - t^2 = 4 \quad \text{--- (3)}$$

From (1) $\lambda = -t$

\therefore from (2)

$$2(-t)t + t^2 = -4$$

$$-2t^2 + t^2 = -4$$

$$\Rightarrow -t^2 = -4$$

$$\Rightarrow t^2 = 4$$

$$\Rightarrow t = \pm 2$$